

a first sensor configured to receive signals representing a force applied to the contact portion;

an actuator coupled to the link, the actuator configured to impart a haptic feedback to the link; and

a second sensor coupled to the interface portion, the second sensor configured to detect a position of the contact portion, the second sensor including an encoder configured to output a position signal including data values associated with a graphical representation of the position, the actuator configured to impart the haptic feedback based on the position signal.--

REMARKS

Entry and consideration of the foregoing amendment is respectfully requested.

The Commissioner is hereby authorized to charge any appropriate fees under 37 C.F.R. §§1.16, 1.17, and 1.21 that may be required by this paper, and to credit any overpayment, to Deposit Account No. 03-3117.


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